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# THE CONE OF $\mathcal{Z}$-TRANSFORMATIONS ON THE LORENTZ CONE* 

SÁNDOR Z. NÉMETH ${ }^{\dagger}$ AND M. SEETHARAMA GOWDA ${ }^{\ddagger}$


#### Abstract

In this paper, we describe the structural properties of the cone of $\mathcal{Z}$-transformations on the Lorentz cone in terms of the semidefinite cone and copositive/completely positive cones induced by the Lorentz cone and its boundary. In particular, we describe its dual as a slice of the semidefinite cone as well as a slice of the completely positive cone of the Lorentz cone. This provides an example of an instance where a conic linear program on a completely positive cone is reduced to a problem on the semidefinite cone.


Key words. $\mathcal{Z}$-transformation, Lorentz cone, semidefinite cone, copositive cone, completely positive cone

AMS subject classifications. $90 \mathrm{C} 33,15 \mathrm{~A} 48$

1. Introduction. Given a proper cone $\mathcal{K}$ in a finite dimensional real Hilbert space $(\mathcal{H},\langle\cdot, \cdot\rangle)$, a linear transformation $A: \mathcal{H} \rightarrow \mathcal{H}$ is said to be a $\mathcal{Z}$-transformation on $\mathcal{K}$ if

$$
\left[x \in \mathcal{K}, y \in \mathcal{K}^{*}, \text { and }\langle x, y\rangle=0\right] \Rightarrow\langle A x, y\rangle \leq 0
$$

where $\mathcal{K}^{*}$ denotes the dual of $\mathcal{K}$ in $\mathcal{H}$. Such transformations appear in various areas including economics, dynamical systems, optimization, see e.g., $[3,2,12,9]$ and the references therein. When $\mathcal{H}$ is $\mathbb{R}^{n}$ and $\mathcal{K}$ is the nonnegative orthant, $\mathcal{Z}$-transformations become $\mathcal{Z}$-matrices, which are square matrices with nonpositive off-diagonal entries.

The set $\mathcal{Z}(\mathcal{K})$ of all $\mathcal{Z}$-transformations on $\mathcal{K}$ is a closed convex cone in the space of all (bounded) linear transformations on $\mathcal{H}$. Given their appearance and importance in various areas, describing/characterizing elements of $\mathcal{Z}(\mathcal{K})$ and its interior, boundary, dual, etc., is of interest. An early result of Schneider and Vidyasagar [16] asserts that $A$ is a $\mathcal{Z}$-transformation on $\mathcal{K}$ if and only if $e^{-t A}(\mathcal{K}) \subseteq \mathcal{K}$ for all $t \geq 0$; consequently,

$$
\begin{equation*}
\mathcal{Z}(\mathcal{K})=\overline{\mathbb{R} I-\pi(\mathcal{K})} \tag{1.1}
\end{equation*}
$$

where $\pi(\mathcal{K})$ denotes the set of all linear transformations that leave $\mathcal{K}$ invariant, $I$ denotes the identity transformation, and overline denotes the closure. To see another description of $\mathcal{Z}(\mathcal{K})$, let $\operatorname{LL}(\mathcal{K}):=\mathcal{Z}(\mathcal{K}) \cap-\mathcal{Z}(\mathcal{K})$ denote the lineality space of $\mathcal{Z}(\mathcal{K})$, the elements of which are called Lyapunov-like transformations. Then the inclusions

$$
\mathbb{R} I-\pi(\mathcal{K}) \subseteq \mathrm{LL}(\mathcal{K})-\pi(\mathcal{K}) \subseteq \mathcal{Z}(\mathcal{K})=\overline{\mathbb{R} I-\pi(\mathcal{K})}
$$

imply that

$$
\mathcal{Z}(\mathcal{K})=\overline{\operatorname{LL}(\mathcal{K})-\pi(\mathcal{K})}
$$

As the cones $\mathcal{Z}(\mathcal{K}), \pi(\mathcal{K})$, and $\operatorname{LL}(\mathcal{K})$ are generally difficult to describe for an arbitrary proper cone $\mathcal{K}$, we consider special cases. When $\mathcal{K}$ is the nonnegative orthant, $\mathcal{Z}(\mathcal{K})$ consists of square matrices with nonpositive off-diagonal entries, $\pi(\mathcal{K})$ consists of nonnegative matrices, and $\operatorname{LL}(\mathcal{K})$ consists of diagonal matrices. Consequently, proper polyhedral cones can be handled via isomorphism arguments. Moving away from

[^0]proper polyhedral cones, in this paper, we focus on the Lorentz cone (also called the ice-cream cone or the second-order cone as it is induced by the 2-norm) in the Euclidean space $\mathbb{R}^{n}, n>1$, defined by:
\[

$$
\begin{equation*}
\mathcal{L}:=\left\{(t, u)^{\top}: t \in \mathbb{R}, u \in \mathbb{R}^{n-1}, t \geq\|u\|\right\} \tag{1.2}
\end{equation*}
$$

\]

This, being an example of a symmetric cone, appears prominently in conic optimization [1]. For this cone, Stern and Wolkowicz [17] have shown that $A \in \mathcal{Z}(\mathcal{L})$ if and only if for some real number $\gamma$, the matrix $\gamma J-\left(J A+A^{\top} J\right)$ is positive semidefinite, where $J$ is the diagonal matrix $\operatorname{diag}(1,-1,-1, \ldots,-1)$. Another result of Stern and Wolkowicz ([18], Theorem 4.2) asserts that

$$
\begin{equation*}
\mathcal{Z}(\mathcal{L})=\operatorname{LL}(\mathcal{L})-\pi(\mathcal{L}) \tag{1.3}
\end{equation*}
$$

(Going in the reverse direction, in a recent paper, Kuzma et al., [13] have shown that for an irreducible symmetric cone $\mathcal{K}$, the equality $\mathcal{Z}(\mathcal{K})=\mathrm{LL}(\mathcal{K})-\pi(\mathcal{K})$ holds only when $\mathcal{K}$ is isomorphic to $\mathcal{L}$.) Characterizations of $\pi(\mathcal{L})$ and $\operatorname{LL}(\mathcal{L})$ appear, respectively, in [14] and [20].

In this paper, we describe $\mathcal{Z}(\mathcal{L})$ and its interior, boundary, and dual in terms of the semidefinite cone and the so-called copositive and completely positive cones induced by $\mathcal{L}$ (or its boundary $\partial(\mathcal{L})$ ), see below for the definitions. In particular, we describe the dual of $\mathcal{Z}(\mathcal{L})$ as a slice of the semidefinite cone and also of the completely positive cone of $\mathcal{L}$. This provides an example of an instance where a conic linear optimization problem over a completely positive cone is reduced to a semidefinite problem. To elaborate, consider $\mathbb{R}^{n}$, the Euclidean $n$-space of (column) vectors with the usual inner product, $\mathbb{R}^{n \times n}$, the space of all real $n \times n$ matrices with the inner product $\langle X, Y\rangle=\operatorname{tr}\left(X^{\top} Y\right)$, and $\mathcal{S}^{n}$, the subspace of all real $n \times n$ symmetric matrices in $\mathbb{R}^{n \times n}$. Corresponding to a closed cone $\mathcal{C}$ (which is not necessarily convex) in $\mathbb{R}^{n}$, let

$$
\mathcal{E}_{\mathcal{C}}:=\operatorname{copos}(\mathcal{C}):=\left\{A \in \mathcal{S}^{n}: x^{\top} A x \geq 0 \text { for all } x \text { in } \mathcal{C}\right\}
$$

denote the copositive cone of $\mathcal{C}$ and

$$
\mathcal{K}_{\mathcal{C}}:=\operatorname{compos}(\mathcal{C}):=\left\{\sum_{u \in U} u u^{\top}: U \text { is a finite subset of } \mathcal{C}\right\}
$$

denote the completely positive cone of $\mathcal{C}$. When $\mathcal{C}=\mathbb{R}^{n}$, these two cones coincide with the semidefinite cone $\mathcal{S}_{+}^{n}$ (consisting of all real $n \times n$ symmetric positive semidefinite matrices); when $\mathcal{C}=\mathbb{R}_{+}^{n}$, these reduce, respectively, to the (standard) copositive cone and completely positive cone. All these cones appear prominently in conic optimization. A result of Burer [5] (see also, [4, 7]) says that any nonconvex quadratic programming problem over a closed cone with additional linear and binary constraints can be reformulated as a linear program over a suitable completely positive cone. For this and other reasons, there is a strong interest in understanding copositive and completely positive cones. For the closed convex cones $\mathcal{E}_{\mathcal{C}}$ and $\mathcal{K}_{\mathcal{C}}$, various structural properties (such as the interior, boundary) as well as duality, irreducibility, and homogeneity properties, have been investigated in the literature, see for example, $[19,6,8,11]$. Taking $\mathcal{C}$ to be one of $\mathbb{R}^{n}, \mathcal{L}$, or $\partial(\mathcal{L})$, we show that

$$
\begin{equation*}
\mathcal{Z}(\mathcal{L})^{*}=\left\{B \in \mathbb{R}^{n \times n}:\langle B, I\rangle=0,-J B \in \mathcal{K}_{\mathcal{C}}\right\} \tag{1.4}
\end{equation*}
$$

and deduce the equality of slices

$$
\begin{equation*}
\left\{X \in \mathbb{R}^{n \times n}:\langle J, X\rangle=0, X \in \mathcal{S}_{+}^{n}\right\}=\left\{X \in \mathbb{R}^{n \times n}:\langle J, X\rangle=0, X \in \mathcal{K}_{\mathcal{C}}\right\} \tag{1.5}
\end{equation*}
$$

2. Preliminaries. In a (finite dimensional real) Hilbert space $(\mathcal{H},\langle\cdot, \cdot\rangle)$, a nonempty set $\mathcal{C}$ is said to be a closed cone if it closed and $t x \in \mathcal{C}$ whenever $x \in \mathcal{C}$ and $t \geq 0$ in $\mathbb{R}$. Throughout this paper, $\mathcal{C}$ denotes a closed cone.
A nonempty set $\mathcal{K}$ is said to be a closed convex cone if it is a closed cone which is also convex. Such a cone is said to be proper if $\mathcal{K} \cap-\mathcal{K}=\{0\}$ and has nonempty interior. Corresponding to a closed convex cone $\mathcal{K}$, we define its dual in $\mathcal{H}$ as the set

$$
\mathcal{K}^{*}=\{x \in \mathcal{H}:\langle x, y\rangle \geq 0, \forall y \in \mathcal{K}\}
$$

We say that a linear transformation $A: \mathcal{H} \rightarrow \mathcal{H}$ is copositive on $\mathcal{K}$ if $\langle A x, x\rangle \geq 0$ for all $x \in \mathcal{K}$. We also let $\pi(\mathcal{K})=\{A: A(\mathcal{K}) \subseteq \mathcal{K}\}$, where $A$ denotes a linear transformation on $\mathcal{H}$. For a set $S$ in $\mathcal{H}$, we denote the closure, interior, and the boundary by $\bar{S}, S^{\circ}$, and $\partial(S)$ respectively.

We will be considering closed convex cones in the space $\mathcal{H}=\mathbb{R}^{n}$ which carries the usual inner product and in the space $\mathbb{R}^{n \times n}$ which carries the inner product $\langle X, Y\rangle:=$ $\operatorname{tr}\left(X^{\top} Y\right)$, where the trace of a square matrix is the sum of its diagonal entries. In $\mathbb{R}^{n \times n}, \mathcal{S}^{n}$ denotes the subspace of all symmetric matrices and $\mathcal{A}^{n}$ denotes the subspace of all skew-symmetric matrices. We note that $\mathbb{R}^{n \times n}$ is the orthogonal direct sum of $\mathcal{S}^{n}$ and $\mathcal{A}^{n}$.

We recall some (easily verifiable) properties of the Lorentz cone $\mathcal{L}$ given by (1.2). $\mathcal{L}$ is a self-dual cone in $\mathbb{R}^{n}$, that is, $\mathcal{L}^{*}=\mathcal{L}$; its interior and boundary are given, respectively, by

$$
\begin{gathered}
\mathcal{L}^{\circ}=\left\{(t, u)^{\top}: t>\|u\|\right\} \\
\partial(\mathcal{L})=\left\{(t, u)^{\top}: t=\|u\|\right\}=\left\{\alpha(1, u)^{\top}: \alpha \geq 0,\|u\|=1\right\} .
\end{gathered}
$$

We also have

$$
\begin{equation*}
[0 \neq x, y \in \mathcal{L},\langle x, y\rangle=0] \Rightarrow x=\alpha(1, u)^{\top} \text { and } y=\beta(1,-u)^{\top}, \tag{2.1}
\end{equation*}
$$

for some $\alpha, \beta>0$ and $\|u\|=1$.

For a closed cone $\mathcal{C}$ in $\mathbb{R}^{n}$, we consider the copositive cone $\mathcal{E}_{\mathcal{C}}$ and the completely positive cone $\mathcal{K}_{\mathcal{C}}$ (defined in the Introduction). Note that these are cones of symmetric matrices.

In the Hilbert space $\mathcal{S}^{n}$ (which carries the inner product from $\mathbb{R}^{n \times n}$ ), the following hold.
(1) $\mathcal{K}_{\mathcal{C}}$ is the dual cone of $\mathcal{E}_{\mathcal{C}}$ [19].
(2) When $\mathcal{C}-\mathcal{C}=\mathbb{R}^{n}$, both $\mathcal{E}_{\mathcal{C}}$ and $\mathcal{K}_{\mathcal{C}}$ are proper cones ([10], Proposition 2.2). In particular, this holds when $\mathcal{C}$ is one of $\mathbb{R}^{n}, \mathcal{L}$, or $\partial(\mathcal{L})$.
(3) We have $\mathcal{S}_{+}^{n}=\mathcal{E}_{\mathbb{R}^{n}} \subset \mathcal{E}_{\mathcal{L}} \subset \mathcal{E}_{\partial(\mathcal{L})}$, or equivalently, $\mathcal{K}_{\partial(\mathcal{L})} \subset \mathcal{K}_{\mathcal{L}} \subset \mathcal{K}_{\mathbb{R}^{n}}=\mathcal{S}_{+}^{n}$.
3. Main results. In this section, we provide a closure-free description of $\mathcal{Z}(\mathcal{L})$ and, additionally, describe the dual, interior, and the boundary of $\mathcal{Z}(\mathcal{L})$. We recall that $J=\operatorname{diag}(1,-1,-1, \ldots,-1)$ and $\mathcal{A}^{n}$ denotes the set of all skew-symmetric matrices in $\mathbb{R}^{n \times n}$.

Theorem 3.1. Let $\mathcal{C}$ denote one of $\mathbb{R}^{n}, \mathcal{L}$, or $\partial(\mathcal{L})$. Then,

$$
\begin{equation*}
\mathcal{Z}(\mathcal{L})=\mathbb{R} I-J\left(\mathcal{E}_{\mathcal{C}}+\mathcal{A}^{n}\right) . \tag{3.1}
\end{equation*}
$$

Proof. Let $A \in \mathcal{Z}(\mathcal{L})$. From the result of Stern and Wolkowicz [17] mentioned in the Introduction, we have

$$
2 \gamma J-\left(J A+A^{\top} J\right)=2 P
$$

for some $\gamma \in \mathbb{R}$ and $P \in \mathcal{S}_{+}^{n}$. Hence, $J A+(J A)^{\top}=2(\gamma J-P)$, which implies

$$
\begin{equation*}
2 J A=J A+(J A)^{\top}-\left[(J A)^{\top}-J A\right]=2(\gamma J-P)-2 Q, \tag{3.2}
\end{equation*}
$$

where $2 Q=(J A)^{\top}-J A$ is skew-symmetric. Since $J^{2}=I$, this leads to

$$
A=\gamma I-J(P+Q),
$$

where $P \in \mathcal{S}_{+}^{n}$ and $Q \in \mathcal{A}^{n}$. As $\mathcal{S}_{+}^{n} \subset \mathcal{E}_{\mathcal{L}} \subset \mathcal{E}_{\partial(\mathcal{L})}$, this proves that

$$
\begin{equation*}
\mathcal{Z}(\mathcal{L}) \subseteq \mathbb{R} I-J\left(\mathcal{S}_{+}^{n}+\mathcal{A}^{n}\right) \subseteq \mathbb{R} I-J\left(\mathcal{E}_{\mathcal{L}}+\mathcal{A}^{n}\right) \subseteq \mathbb{R} I-J\left(\mathcal{E}_{\partial(\mathcal{L})}+\mathcal{A}^{n}\right) \tag{3.3}
\end{equation*}
$$

Now, to see the reverse inclusions, suppose $A=\gamma I-J(P+Q)$ for some $\gamma \in \mathbb{R}$, $P \in \mathcal{E}_{\partial(\mathcal{L})}$, and $Q$ skew-symmetric. Let $0 \neq x, y \in \mathcal{L}$ with $\langle x, y\rangle=0$. By (2.1), $x$ and $y$ are in $\partial(\mathcal{L})$, and $J y$ is a positive multiple of $x$. Hence, $\langle P x, J y\rangle \geq 0$ as $P \in \mathcal{E}_{\partial(\mathcal{L})}$ and $\langle Q x, J y\rangle=0$ as $Q$ is skew-symmetric. Thus,

$$
\langle A x, y\rangle=\gamma\langle x, y\rangle-\langle J P x, y\rangle+\langle J Q x, y\rangle=-\langle P x, J y\rangle+\langle Q x, J y\rangle \leq 0
$$

This shows that $A \in \mathcal{Z}(\mathcal{L})$ and so, inclusions in (3.3) turn into equalities. Thus we have (3.1).
Remarks. From the above theorem, we have

$$
\mathbb{R} I-J\left(\mathcal{S}_{+}^{n}+\mathcal{A}^{n}\right)=\mathbb{R} I-J\left(\mathcal{E}_{\mathcal{L}}+\mathcal{A}^{n}\right)=\mathbb{R} I-J\left(\mathcal{E}_{\partial(\mathcal{L})}+\mathcal{A}^{n}\right) .
$$

Multiplying throughout by $J$ and noting $-\mathcal{A}^{n}=\mathcal{A}^{n}$, we get the equality of sets

$$
\left(\mathbb{R} J-\mathcal{S}_{+}^{n}\right)+\mathcal{A}^{n}=\left(\mathbb{R} J-\mathcal{E}_{\mathcal{L}}\right)+\mathcal{A}^{n}=\left(\mathbb{R} J-\mathcal{E}_{\partial(\mathcal{L})}\right)+\mathcal{A}^{n},
$$

where each set is a sum of $\mathcal{A}^{n}$ and a subset of $\mathcal{S}^{n}$. Since $\mathbb{R}^{n \times n}=\mathcal{S}^{n}+\mathcal{A}^{n}$ is an (orthogonal) direct sum decomposition, we see that

$$
\begin{equation*}
\mathbb{R} J-\mathcal{S}_{+}^{n}=\mathbb{R} J-\mathcal{E}_{\mathcal{L}}=\mathbb{R} J-\mathcal{E}_{\partial(\mathcal{L})} . \tag{3.4}
\end{equation*}
$$

These equalities can also be established via different arguments. A result of Loewy and Schneider [14] asserts that $A$ symmetric matrix $X$ is copositive on $\mathcal{L}$ if and only if there exists $\mu \geq 0$ such that $X-\mu J \in \mathcal{S}_{+}^{n}$. (This is essentially a consequence of the so-called S-Lemma [15]: If $A$ and $B$ are two symmetric matrices with $\left\langle A x_{0}, x_{0}\right\rangle>0$ for some $x_{0}$ and $\langle A x, x\rangle \geq 0 \Rightarrow\langle B x, x\rangle \geq 0$, then there exists $\mu \geq 0$ such that $B-\mu A$ is positive semidefinite.) This result gives the equality

$$
\mathcal{E}_{\mathcal{L}}=\mathcal{S}_{+}^{n}+\mathbb{R}_{+} J
$$

and consequently $\mathbb{R} J-\mathcal{S}_{+}^{n}=\mathbb{R} J-\mathcal{E}_{\mathcal{L}}$. The equality

$$
\mathcal{E}_{\partial(\mathcal{L})}=\mathcal{S}_{+}^{n}+\mathbb{R} J
$$

can be seen via an application of Finsler' theorem [15] that says that if $A$ and $B$ are two symmetric matrices with $[x \neq 0,\langle A x, x\rangle=0] \Rightarrow\langle B x, x\rangle>0$, then there exists $\mu \in \mathbb{R}$ such that $B+\mu A$ is positive semidefinite. (For $M \in \mathcal{E}_{\partial(\mathcal{L})}$ and vectors $u, v \in \mathcal{L}^{\circ}$, one has $\langle J x, x\rangle=0 \Rightarrow\left\langle M_{k} x, x\right\rangle>0$, where $k$ is a natural number and $M_{k}:=M+\frac{1}{k} u v^{\top}$. When $M_{k}+\mu_{k} J$ is positive semidefinite for all $k$, it follows that the sequence $\mu_{k}$ is bounded. One can then use a limiting argument.) From this equality, one gets $\mathbb{R} J-\mathcal{S}_{+}^{n}=\mathbb{R} J-\mathcal{E}_{\partial(\mathcal{L})}$.

Our next result deals with the dual of $\mathcal{Z}(\mathcal{L})$.
Theorem 3.2. Let $\mathcal{C}$ denote one of $\mathbb{R}^{n}, \mathcal{L}$, or $\partial(\mathcal{L})$. Then,

$$
\mathcal{Z}(\mathcal{L})^{*}=\left\{B \in \mathbb{R}^{n \times n}:\langle B, I\rangle=0,-J B \in \mathcal{K}_{\mathcal{C}}\right\}
$$

In particular, (1.5) holds.

Proof. We fix $\mathcal{C}$. From (3.1), we see that $B \in \mathcal{Z}(\mathcal{L})^{*}$ if and only if

$$
0 \leq\langle B, \gamma I-J(P+Q)\rangle
$$

for all $\gamma$ real, $P$ in $\mathcal{E}_{\mathcal{C}}$, and $Q$ in $\mathcal{A}^{n}$. Clearly, this holds if and only if

$$
\langle B, I\rangle=0,\langle-J B, P\rangle \geq 0, \text { and }\langle-J B, Q\rangle=0
$$

for all $\gamma, P$, and $Q$ specified above. Now, with the observation that a (real) matrix is orthogonal to all skew-symmetric matrices in $\mathbb{R}^{n \times n}$ if and only if it is symmetric, this further simplifies to

$$
\langle B, I\rangle=0 \text { and }-J B \in \mathcal{E}_{\mathcal{C}}^{*}
$$

where $\mathcal{E}_{\mathcal{C}}^{*}$ is the dual of $\mathcal{E}_{\mathcal{C}}$ computed in $\mathcal{S}^{n}$. Since $\mathcal{K}_{\mathcal{C}}=\mathcal{E}_{\mathcal{C}}^{*}$ in $\mathcal{S}^{n}$, we see that $B \in \mathcal{Z}(\mathcal{L})^{*}$ if and only if $\langle B, I\rangle=0$ and $-J B \in \mathcal{K}_{\mathcal{C}}$. This completes the proof.

We remark that (1.5) can be deduced directly from (3.4) by taking the duals in $\mathcal{S}^{n}$.
In our final result, we describe the interior and boundary of $\mathcal{Z}(\mathcal{L})$. First, we recall some definitions from [9]. Let

$$
\Omega:=\{(x, y) \in \mathcal{L} \times \mathcal{L}:\|x\|=1=\|y\| \text { and }\langle x, y\rangle=0\}
$$

It is easy to see that $\Omega$ is compact and, from (2.1),

$$
\begin{equation*}
\Omega=\{(x, J x): x \in \partial(\mathcal{L}),\|x\|=1\} \tag{3.5}
\end{equation*}
$$

For any $A \in \mathbb{R}^{n \times n}$, let

$$
\gamma(A):=\max \{\langle A x, y\rangle:(x, y) \in \Omega\}
$$

Note that $A \in \mathcal{Z}(\mathcal{L})$ if and only if $\gamma(A) \leq 0$. We say that $A \in \mathbb{R}^{n \times n}$ is a strict- $\mathcal{Z}$ transformation on $\mathcal{L}$ if

$$
[0 \neq x, y \in \mathcal{L},\langle x, y\rangle=0] \Rightarrow\langle A x, y\rangle<0
$$

The set of all such transformations is denoted by $\operatorname{str}(\mathcal{Z}(\mathcal{L}))$. For $A \in \mathbb{R}^{n \times n}$, the following statements are shown in [9], Theorem 3.1:

$$
\gamma(A)<0 \Longleftrightarrow A \in \mathcal{Z}(\mathcal{L})^{\circ} \Longleftrightarrow A \in \operatorname{str}(\mathcal{Z}(\mathcal{L}))
$$

and

$$
\gamma(A)=0 \Longleftrightarrow A \in \partial(\mathcal{Z}(\mathcal{L}))
$$

Recall that $\mathcal{E}_{\mathcal{L}}$ consists of all symmetric matrices that are copositive on $\mathcal{L}$. We say that a symmetric matrix $P$ is strictly copositive on $\mathcal{L}$ if $0 \neq x \in \mathcal{L} \Rightarrow\langle P x, x\rangle>0$; the set of all such matrices is denoted by $\operatorname{str}\left(\mathcal{E}_{\mathcal{L}}\right)$. Similarly, one defines $\operatorname{str}\left(\mathcal{E}_{\partial(\mathcal{L})}\right)$.

Corollary 3.3. The following statements hold:

$$
\mathcal{Z}(\mathcal{L})^{\circ}=\operatorname{str}(\mathcal{Z}(\mathcal{L}))=\mathbb{R} I-J\left(\operatorname{str}\left(\mathcal{E}_{\partial(\mathcal{L})}\right)+\mathcal{A}^{n}\right)
$$

and

$$
\partial(\mathcal{Z}(\mathcal{L}))=\mathbb{R} I-J\left(\partial_{*}\left(\mathcal{E}_{\partial(\mathcal{L})}\right)+\mathcal{A}^{n}\right)
$$

where $\partial_{*}\left(\mathcal{E}_{\partial(\mathcal{L})}\right)$ denotes the boundary of $\mathcal{E}_{\partial(\mathcal{L})}$ in $\mathcal{S}^{n}$.

Proof. We first deal with the interior of $\mathcal{Z}(\mathcal{L})$. The equality

$$
\left\{A \in \mathbb{R}^{n \times n}: \gamma(A)<0\right\}=\mathcal{Z}(\mathcal{L})^{\circ}=\operatorname{str}(\mathcal{Z}(\mathcal{L}))
$$

has already been observed in [9], Theorem 3.1. To see the first assertion, we show that $\gamma(A)<0$ if and only if $A=\theta I-J(P+Q)$ for some $\theta \in \mathbb{R}, P$ (symmetric) strictly copositive on $\partial(\mathcal{L})$, and $Q$ skew-symmetric. Suppose $\gamma(A)<0$. Then, for any $\theta \in \mathbb{R}$,

$$
\max \{\langle(A-\theta I) x, y\rangle:(x, y) \in \Omega\}<0
$$

which, from (3.5) becomes

$$
\min \{\langle J(\theta I-A) x, x\rangle: x \in \partial(\mathcal{L}),\|x\|=1\}>0
$$

Now, fix $\theta$ and let $J(\theta I-A)=P+Q$, where $P \in \mathcal{S}^{n}$ and $Q \in \mathcal{A}^{n}$. As $\langle Q x, x\rangle=0$ for any $x$, the above inequality implies that $\min \{\langle P x, x\rangle: x \in \partial(\mathcal{L}),\|x\|=1\}>0$. This proves that $P$ is strictly copositive on $\partial(\mathcal{L})$. Rewriting $J(\theta I-A)=P+Q$, we see that $A=\theta I-J(P+Q)$ which is of the required form.
To see the converse, suppose $A=\theta I-J(P+Q)$, where $\theta \in \mathbb{R}, P$ (symmetric) strictly copositive on $\partial(\mathcal{L})$, and $Q$ skew-symmetric. Using (3.5), we can easily verify that $\gamma(A)<0$. Thus, $A \in \operatorname{str}(\mathcal{Z}(\mathcal{L}))$.
An argument similar to the above will show that $\gamma(A)=0$ if and only if $A=\theta I-$ $J(P+Q)$ for some $\theta \in \mathbb{R}, P \in \partial_{*}\left(\mathcal{E}_{\partial(\mathcal{L})}\right)$, and $Q$ skew-symmetric. This gives the statement regarding the boundary of $\mathcal{Z}(\mathcal{L})$.

We end the paper with a remark dealing with conic linear programs. Motivated by the result of Burer (mentioned in the Introduction), we consider a conic linear program on a completely positive cone $\mathcal{K}_{\mathcal{C}}$ (where $\mathcal{C}$ is a closed cone):

$$
\min \left\{\langle c, x\rangle: A x=b, x \in \mathcal{K}_{\mathcal{C}}\right\}
$$

While such a problem is generally hard to solve, we ask: (When) can we replace $\mathcal{K}_{\mathcal{C}}$ by $\mathcal{S}_{+}^{n}$ and thus reduce the above problem to the semidefinite programming problem $\min \left\{\langle c, x\rangle: A x=b, x \in \mathcal{S}_{+}^{n}\right\}$ ? Just replacing $\mathcal{K}_{\mathcal{C}}$ by $\mathcal{S}_{+}^{n}$ without handling the constraint $A x=b$ is not viable as $\mathcal{K}_{\mathcal{C}}=\mathcal{S}_{+}^{n}$ if and only if $\mathcal{C} \cup-\mathcal{C}=\mathbb{R}^{n}$ (which fails to hold when $n>1$ and $\mathcal{C}$ is pointed), see [11]. While we do not answer this broad question, we point out, as a consequence of (1.5) that for any $C \in \mathcal{S}^{n}$,

$$
\min \left\{\langle C, X\rangle:\langle X, J\rangle=0, X \in \mathcal{K}_{\mathcal{L}}\right\}=\min \left\{\langle C, X\rangle:\langle X, J\rangle=0, X \in \mathcal{S}_{+}^{n}\right\}
$$

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